EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S99	0	gravit\$8 near3 (compensat\$4 control\$4) with position near3 control\$4 with (output and input) and @pd> "20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:41
S102	0	(position\$4 same (gravity gravitation\$4)) near6 ((measur\$6 detect\$4 sens\$4) same (control\$4 actuat\$4)) same (spring pulley motor tension) and (@ad<"20030807" @rlad<"20030807") and @pd>"20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR		2009/02/16 19:42
S101	0	control\$4) same position	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:42
S100	0	gravit\$8 near3 (compensat\$4 control\$4) with position near3 control\$4 with (output input signal) and (@ad< "20030807" @rlad< "20030807") and @pd> "20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:42
S104	1	(position location displac\$6) near3 (measur\$6 sensor sensing detect\$4) and (control \$4 actuat\$4) and gravity near3 (compensat\$4 reduc\$4 limit\$4 correct\$4 control\$4 actuat\$4) and gravity with input with output with (position location displac\$6) and (@ad<"20030807" @rlad<"20031101"	DERWENT;	OR	ON	2009/02/16 19:43

S103	0	position\$4 near6 ((measur\$6 detect\$4 sens\$4) same (control\$4 actuat\$4)) and (gravity gravitation\$4) near6 (correct\$4 compensat\$4 limit \$4 reduc\$6 force) and (spring same pulley same motor same tension) and (@ad<"20030807" @rlad<"20030807") and @pd>"20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	O	2009/02/16 19:43
S107	О	(position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) and gravity near3 (compensat\$4 reduc\$4 limit\$4 correct\$4 control\$4 actuat\$4) and gravity with input with output with (position location displac \$6) and gravity with (spring tension pulley motor) and (@ad<"20030807" @rlad<"20030807") and @pd>"20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR		2009/02/16 19:45
S106	0	(position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) and gravity near3 (compensat\$4 reduc\$4 limit\$4 correct\$4 control\$4 actuat\$4) and gravity with input with output with (position location displac \$6) and (@ad<"20030807" @rlad<"20030807") and @pd>"20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON The state of th	2009/02/16 19:45
S105	1	(position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4) and (control \$4 actuat\$4)) and gravity near3 (compensat\$4 reduc\$4 limit\$4 correct\$4 control\$4 actuat\$4) and gravity with input with output with (position location displac\$6) and (@ad< "20030807" @rlad< "20030807") and @pd> "20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:45
S109	0	gravity same (spring and string and motor) and (@ad< "20030807" @rlad< "20030807") and @pd> "20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:47

S108	1	(position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) and gravity near3 (compensat\$4 reduc\$4 limit\$4 correct\$4 control\$4 actuat\$4) and gravity with ((spring pulley) and (tension motor)) and (@ad<"20030807" @rlad<"20030807") and @pd>"20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:47
S110	0	(position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4) and (control \$4 actuat\$4)) with (gravity gravitational) near3 (compensat\$4 force control \$4 actuat\$4) and (@ad<"20030807" @rlad<"20030807") and @pd>"20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:48
S111	0	"700"/\$ and (position location displac\$6) near6 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) and (gravity gravitational) near3 (compensat\$4 force control\$4 actuat\$4) with (spring pulley tension motor) and (@ad<"20030807" @rlad<"20030807") and @pd>"20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:49
S114	0	"33"/\$ and (position location displac\$6) near6 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) and (gravity gravitational) near3 (compensat\$4 force control\$4 actuat\$4) with (spring pulley tension motor) and (@ad< "20030807" @rlad< "20030807") and @pd> "20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:50
S113	0	"333"/\$ and (position location displac\$6) near6 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) and (gravity gravitational) near3 (compensat\$4 force control\$4 actuat\$4) with (spring pulley tension motor) and (@ad< "20030807" @rlad< "20030807") and @pd> "20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:50

S112	0	"318"/\$ and (position location displac\$6) near6 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) and (gravity gravitational) near3 (compensat\$4 force control\$4 actuat\$4) with (spring pulley tension motor) and (@ad< "20030807" @rlad< "20030807") and @pd> "20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:50
S115	1	"702"/\$ and (position location displac\$6) near6 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) and (gravity gravitational) near3 (compensat\$4 force control\$4 actuat\$4) with (spring pulley tension motor) and (@ad<"20030807" @rlad<"20030807") and @pd> "20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:53
S119	0	"318"/\$ and gravit\$8 near3 (compensat\$4 control\$4) with position near3 control\$4 with (output input signal) and (@ad< "20030807" @rlad< "20030807") and @pd> "20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:54
S118	0	"33"/\$ and gravit\$8 near3 (compensat\$4 control\$4) with position near3 control\$4 with (output input signal) and (@ad< "20030807" @rlad< "20030807") and @pd> "20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:54
S117	0	"700"/\$ and gravit\$8 near3 (compensat\$4 control\$4) with position near3 control\$4 with (output input signal) and (@ad< "20030807" @rlad< "20030807") and @pd> "20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:54
S116	0	"702"/\$ and gravit\$8 near3 (compensat\$4 control\$4) with position near3 control\$4 with (output input signal) and (@ad< "20030807" @rlad< "20030807") and @pd> "20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:54

S120	0	gravit\$8 near3 (compensat\$4 control\$4) with position near3 control\$4 with (output input signal) and (@ad<"20030807" @rlad<"20030807") and @pd>"20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 19:55
mS121	3	(position location displac\$6) near6 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) and (gravity gravitational) near3 (compensat\$4 force control \$4 actuat\$4) with (spring pulley tension motor) and (@ad< "20030807" @rlad< "20030807") and @pd> "20081101"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR		2009/02/16 19:56
	2	"33"/\$ and (position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) same (gravity gravitational) near3 (compensat\$4 force control\$4 actuat\$4) same (spring pulley tension motor) and (@ad< "20030807" @rlad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR		2009/02/16 20:00
S123	41	(position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) same (gravity gravitational) near3 (compensat\$4 force control \$4 actuat\$4) same (spring pulley tension motor) and (@ad< "20030807" @rlad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR		2009/02/16 20:00
S122	690	(position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) and (gravity gravitational) near3 (compensat\$4 force control \$4 actuat\$4) same (spring pulley tension motor) and (@ad< "20030807" @rlad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	. ON	2009/02/16 20:00

S127	1	"702"/\$ and (position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) same (gravity gravitational) near3 (compensat\$4 force control\$4 actuat\$4) same (spring pulley tension motor) and (@ad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 20:01
mS126	6	"700"/\$ and (position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) same (gravity gravitational) near3 (compensat\$4 force control\$4 actuat\$4) same (spring pulley tension motor) and (@ad< "20030807" @rlad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	NON	2009/02/16 20:01
mS1 25	8	"318"/\$ and (position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) same (gravity gravitational) near3 (compensat\$4 force control\$4 actuat\$4) same (spring pulley tension motor) and (@ad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR		2009/02/16 20:01
S128	1400	(position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4 control\$4 actuat\$4) same (control\$4 actuat\$4)) same (gravity gravitational) near3 (compensat\$4 force control \$4 actuat\$4) and (spring pulley tension motor) and (@ad<"20030807" @rlad<"20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 22:45
\$132	1	"702"/\$ and (position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) same (gravity gravitational) near3 (compensat\$4 force control\$4 actuat\$4) and (spring pulley tension motor) and (@ad<"20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 22:56

S131	8	· · · · · · · · · · · · · · · · · · ·	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 22:56
S130	15		US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 22:56
S129	5	S128/\$ and (position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) same (gravity gravitational) near3 (compensat\$4 force control\$4 actuat\$4) and (spring pulley tension motor) and (@ad<"20030807"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/02/16 22:56

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